

1. If a system of linear equations has a solution, we say it is _____.

2. Which of the following is a solution to the system of equations

$$x_1 + x_2 - x_3 - x_4 = 0$$

$$x_1 + x_2 + x_3 + x_4 = 8$$

$$2x_1 - x_2 + x_3 = 0$$

$$x_2 - x_4 = 0$$

- (a) (1, 1, 3, 3)
- (b) (1, 3, 1, 3)
- (c) (3, 3, 1, 1)
- (d) (1, -1, 3, -3)
- (e) (1, -3, 1, -3)
- (f) (-1, 1, -3, 3)

3. Consider the following augmented matrix:

$$\left[\begin{array}{ccccc} 2 & 1 & 2 & 2 & 1 \\ 1 & 2 & -1 & 1 & -1 \\ 4 & 5 & 0 & k & 2 \end{array} \right]$$

For which value of k is the system inconsistent?

- (a) 0
- (b) 1
- (c) 2
- (d) 4
- (e) 6
- (f) It is consistent for all values of k .
- (g) It is inconsistent for all values of k .

4. Find all solutions to the system of equations

$$x_1 + x_2 + 2x_3 + x_4 = 1$$

$$2x_1 + x_3 + x_4 = 0$$

$$x_1 + 2x_2 + x_3 + 2x_4 = 1$$

$$x_1 + x_2 = -1$$

5. Which of the following statements are not necessarily true for a linear transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$?
- (a) If $T(\mathbf{x}) = \mathbf{0}$, then $\mathbf{x} = \mathbf{0}$.
 - (b) $T(\mathbf{0}) = \mathbf{0}$
 - (c) $T(\alpha\mathbf{x}) = \alpha\mathbf{x}$
 - (d) $T(\mathbf{x} + \mathbf{y}) = \mathbf{T}(\mathbf{x}) + \mathbf{T}(\mathbf{y})$
 - (e) A vector rotation through angle θ is a linear transformation.
6. Every linear transformation can be represented by a _____.
7. Define $T(\mathbf{x}) = \mathbf{Ax}$ by the following matrix

$$A = \begin{bmatrix} 1 & 1 \\ 2 & 1 \\ -1 & -3 \end{bmatrix}.$$

Which of the following vectors is not in the range of T ?

- (a) $\begin{bmatrix} 2 \\ 3 \\ -4 \end{bmatrix}$
- (b) $\begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$
- (c) $\begin{bmatrix} -1 \\ 0 \\ 5 \end{bmatrix}$
- (d) $\begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$
- (e) $\begin{bmatrix} 1 \\ 4 \\ 3 \end{bmatrix}$

8. Define

$$T \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right) = \begin{bmatrix} x_1 + x_3 \\ 2x_1 - x_2 + x_3 \\ x_1 - 2x_2 + x_3 \end{bmatrix}.$$

- (a) State the matrix of T .
- (b) Find all values \mathbf{x} where $T(\mathbf{x}) = \mathbf{0}$.