

Math 521 Lecture #37  
§4.5: Hamilton's Equations

The Euler equation for the variational problem

$$J(y) = \int_{t_0}^{t_1} L(t, y, \dot{y}) dt$$

is the second-order ODE

$$L_y - \frac{d}{dx} L_{\dot{y}} = 0.$$

We introduce a **canonical way** to convert this second-order ODE into a system to first-order ODEs.

We keep  $y$  as one variable, and define a new variable, called the **canonical momentum**, by

$$p = L_{\dot{y}}(t, y, \dot{y}).$$

The change of variables from  $(y, \dot{y})$  to  $(y, p)$  is called the **Legendre transformation**.

We seek a system of first order ODEs in the variables  $y$  and  $p$ .

From the definition of  $p$ , the Euler equation becomes

$$\frac{dp}{dx} = L_y.$$

When  $L_{\dot{y}\dot{y}} \neq 0$ , the Implicit Function Theorem guarantees that we can solve  $p = L_{\dot{y}}(t, y, \dot{y})$  for  $\dot{y}$  to get

$$\dot{y} = \phi(t, y, p).$$

The Hamiltonian  $H = -L + \dot{y}L_{\dot{y}}$ , which is a function of  $y$  and  $\dot{y}$ , can now be expressed in terms of  $y$  and  $p$ :

$$H(t, y, p) = -L(t, y, \phi(t, y, p)) + \phi(t, y, p)p.$$

Then

$$\frac{\partial H}{\partial y} = -\frac{\partial L}{\partial y} - \frac{\partial L}{\partial \dot{y}} \frac{\partial \phi}{\partial y} + p \frac{\partial \phi}{\partial y} = -\frac{\partial L}{\partial y} - p \frac{\partial \phi}{\partial y} + p \frac{\partial \phi}{\partial y} = -\frac{\partial L}{\partial y} = -L_y = -\dot{p},$$

and

$$\frac{\partial H}{\partial p} = -\frac{\partial L}{\partial \dot{y}} \frac{\partial \phi}{\partial p} + p \frac{\partial \phi}{\partial p} + \phi = -p \frac{\partial \phi}{\partial p} - p \frac{\partial \phi}{\partial p} + \phi = \phi = \dot{y}.$$

Rewriting these gives a system of first-order ODEs in the variables  $y$  and  $p$ :

$$\dot{y} = \frac{\partial H}{\partial p},$$
$$\dot{p} = -\frac{\partial H}{\partial y}.$$

These are called **Hamilton's equations**.

Example 4.26. Recall that the Lagrangian of the harmonic oscillator is

$$L(t, y, \dot{y}) = \frac{m\dot{y}^2}{2} - \frac{ky^2}{2}.$$

The canonical momentum is defined by

$$p = L_{\dot{y}} = m\dot{y}.$$

This inverts to give

$$\dot{y} = \phi(t, y, p) = \frac{p}{m}.$$

The total energy, or Hamiltonian, of the system in the variables  $y$  and  $p$  is

$$\begin{aligned} H &= -L + \dot{y}L_{\dot{y}} \\ &= -\frac{m\dot{y}^2}{2} + \frac{ky^2}{2} + \dot{y}(m\dot{y}) \\ &= \frac{m\dot{y}^2}{2} + \frac{ky^2}{2} \\ &= \frac{m}{2} \left( \frac{p}{m} \right)^2 + \frac{ky^2}{2} \\ &= \frac{p^2}{2m} + \frac{ky^2}{2}. \end{aligned}$$

Since

$$\frac{\partial H}{\partial y} = ky, \quad \frac{\partial H}{\partial p} = \frac{p}{m},$$

Hamilton's equations are

$$\dot{y} = \frac{\partial H}{\partial p} = \frac{p}{m}, \quad \dot{p} = -\frac{\partial H}{\partial y} = -ky.$$

We can solve this system of first-order ODEs by eliminating the  $t$  variable to obtain a single first-order ODE,

$$\frac{dp}{dy} = \frac{dp/dt}{dy/dt} = \frac{-ky}{p/m} = -\frac{kmy}{p}.$$

Separation of variables then gives

$$pdp = -kmydy$$

so that

$$\frac{p^2}{2} = -\frac{kmy^2}{2} + C.$$

Dividing through by  $m$  gives the Hamiltonian

$$\frac{C}{m} = \frac{p^2}{m} + \frac{ky^2}{2} = H,$$

whose level curves are ellipses in the  $yp$ -plane.

For the general action integral

$$J(y_1, \dots, y_n) = \int_{t_0}^{t_1} L(t, y_1, \dots, y_n, \dot{y}_1, \dots, \dot{y}_n) dt,$$

the canonical momenta are defined by

$$p_i = L_{\dot{y}_i}(t, y_1, \dots, y_n, \dot{y}_1, \dots, \dot{y}_n), \quad i = 1, \dots, n.$$

This determines the Legendre transformation from the variables  $(y_1, \dots, y_n, \dot{y}_1, \dots, \dot{y}_n)$  to the variables  $(y_1, \dots, y_n, p_1, \dots, p_n)$ .

Assuming that the  $n \times n$  matrix with entries  $L_{\dot{y}_i \dot{y}_j}$  is invertible, we can solve  $p_i = L_{\dot{y}_i}(t, y_1, \dots, y_n, \dot{y}_1, \dots, \dot{y}_n)$  for  $\dot{y}_1, \dots, \dot{y}_n$  (via the Implicit Function Theorem) to obtain

$$\dot{y}_i = \phi_i(t, y_1, \dots, y_n, p_1, \dots, p_n), \quad i = 1, \dots, n.$$

The Hamilton in terms of the variables  $y_1, \dots, y_n$  and  $p_1, \dots, p_n$  is then

$$\begin{aligned} H &= -L + \sum_{i=1}^n \dot{y}_i L_{\dot{y}_i} \\ &= -L(t, y_1, \dots, y_n, \phi_1, \dots, \phi_n) + \sum_{i=1}^n \phi_i(t, y_1, \dots, y_n, p_1, \dots, p_n) p_i, \end{aligned}$$

where we have suppressed the dependence of  $\phi_i$  on  $(t, y_1, \dots, y_n, p_1, \dots, p_n)$ .

We can convert the Euler-Lagrange equations (a system of  $n$  second-order ODEs),

$$0 = L_{y_j} - \frac{d}{dt} L_{\dot{y}_j} = L_{y_j} - \frac{dp_j}{dt}, \quad j = 1, \dots, n,$$

into a system of  $2n$  first-order ODEs (Hamilton's equations):

$$\begin{aligned} \frac{\partial H}{\partial y_j} &= -L_{y_j} - \sum_{i=1}^n \frac{\partial L}{\partial \dot{y}_i} \frac{\partial \phi_i}{\partial y_j} + \sum_{i=1}^n \frac{\partial \phi_i}{\partial y_j} p_i \\ &= -L_{y_j} - \sum_{i=1}^n \frac{\partial L}{\partial \dot{y}_i} \frac{\partial \phi_i}{\partial y_j} + \sum_{i=1}^n \frac{\partial \phi_i}{\partial y_j} \frac{\partial L}{\partial \dot{y}_i} \\ &= -L_{y_j} = -\dot{p}_j \end{aligned}$$

and

$$\begin{aligned} \frac{\partial H}{\partial p_j} &= - \sum_{i=1}^n \frac{\partial L}{\partial \dot{y}_i} \frac{\partial \phi_i}{\partial p_j} + \sum_{i=1}^n \frac{\partial \phi_i}{\partial p_i} p_j + \phi_j \\ &= - \sum_{i=1}^n \frac{\partial L}{\partial \dot{y}_i} \frac{\partial \phi_i}{\partial p_j} + \sum_{i=1}^n \frac{\partial \phi_i}{\partial p_i} \frac{\partial L}{\partial \dot{y}_i} + \phi_j \\ &= \phi_j = \dot{y}_j \end{aligned}$$

Thus we obtain the Hamiltonian system of first-order ODEs,

$$\dot{y}_j = \frac{\partial H}{\partial p_j}, \quad \dot{p}_j = -\frac{\partial H}{\partial y_j}, \quad j = 1, \dots, n.$$