

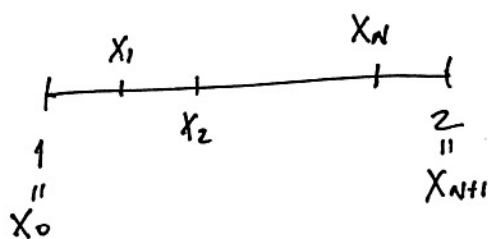
11.4 FINITE DIFFERENCE METHODS FOR Nonlinear Problems.

Consider the nonlinear BVP:

Probl. 1) in section 11.4.

$$\begin{cases} y''(x) + (y'(x))^2 + y(x) = \ln x, & 1 < x < 2 & (1) \\ y(1) = 0, & y(2) = \ln(2). & (2) \end{cases}$$

Grid points:



$$h = \frac{2-1}{N+1} = \frac{1}{N+1}$$

$$x_i = 1 + ih$$

Using centered difference approx for (1)

$$\frac{w_{i+1} - 2w_i + w_{i-1}}{h^2} + \left[\frac{w_{i+1} - w_{i-1}}{2h} \right]^2 + w_i = \ln(x_i)$$

From here the following nonlinear system is obtained,

$i=1$:

$$f_1(w_1, w_2, \dots, w_N) = \frac{w_2 - 2w_1 + w_0}{h^2} + \left[\frac{w_2 - w_0}{2h} \right]^2 + w_1 - \ln(x_1) = 0$$

$i=2$:

$$f_2(w_1, w_2, \dots, w_N) = \frac{w_3 - 2w_2 + w_1}{h^2} + \left[\frac{w_3 - w_1}{2h} \right]^2 + w_2 - \ln(x_2) = 0 \quad (3)$$

$$\vdots$$

$$f_i(w_1, w_2, \dots, w_N) = \frac{w_{i+1} - 2w_i + w_{i-1}}{h^2} + \left[\frac{w_{i+1} - w_{i-1}}{2h} \right]^2 + w_i - \ln(x_i) = 0$$

$$\vdots$$

$$f_N(w_1, w_2, \dots, w_N) = \frac{w_{N+1} - 2w_N + w_{N-1}}{h^2} + \left[\frac{w_{N+1} - w_{N-1}}{2h} \right]^2 + w_N - \ln(x_N) = 0$$

The BVP reduces to find the roots for the vector equation

$$F(\vec{\omega}) = (f_1(\vec{\omega}), \dots, f_n(\vec{\omega})) = \vec{0} \tag{4}$$

where $\vec{\omega} \equiv (\omega_1, \omega_2, \dots, \omega_n)$.

Using Newton method, we transform (4) into a fixed point problem for

$$G(\vec{\omega}) := \vec{\omega}$$

where $G(\vec{\omega}) \equiv \vec{\omega} - J^{-1}(\vec{\omega}) \vec{F}(\vec{\omega}) \tag{5}$

and $J(\vec{\omega}) \equiv \begin{bmatrix} \frac{\partial f_1}{\partial \omega_1} & \frac{\partial f_1}{\partial \omega_2} & \dots & \frac{\partial f_1}{\partial \omega_n} \\ \frac{\partial f_2}{\partial \omega_1} & \frac{\partial f_2}{\partial \omega_2} & \dots & \frac{\partial f_2}{\partial \omega_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_n}{\partial \omega_1} & \frac{\partial f_n}{\partial \omega_2} & \dots & \frac{\partial f_n}{\partial \omega_n} \end{bmatrix}$
↑
Jacobian of vector matrix of function $F(\vec{\omega})$.

Eqn. (5) is used for a functional iteration,

$$G(\vec{\omega}^{(k)}) = \vec{\omega}^{(k-1)} - J^{-1}(\vec{\omega}^{(k-1)}) \vec{F}(\vec{\omega}^{(k-1)})$$

Knowing $\vec{\omega}^{(k-1)}$, the new approx. $\vec{\omega}^{(k)}$ is obtained in two steps:

Step 1: $J(\vec{\omega}^{(k-1)}) \vec{y} = \vec{F}(\vec{\omega}^{(k-1)})$
Step 2: $\vec{x}^{(k)} = \vec{x}^{(k-1)} + \vec{y}$

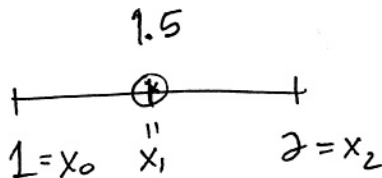
So a key part in the computation is the derivation of the Jacobian, $J(\vec{\omega})$ of $\vec{F}(\vec{\omega})$.

In our particular example,

$$J(\vec{\omega}) = \begin{bmatrix} \left(\frac{-2}{h^2} + 1\right) & \left(\frac{1}{h^2} + \frac{\omega_2 - \omega_0}{h}\right) & 0 & \dots & 0 & \dots & 0 & \dots & 0 \\ \left(\frac{1}{h^2} - \frac{\omega_3 - \omega_1}{h}\right) & \left(-\frac{2}{h^2} + 1\right) & \left(\frac{1}{h^2} + \frac{\omega_3 - \omega_1}{h}\right) & 0 & \dots & \dots & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \left(\frac{1}{h^2} - \frac{\omega_{N+1} - \omega_{N-2}}{h}\right) & \left(-\frac{2}{h^2} + 1\right) & \left(\frac{1}{h^2} + \frac{\omega_{N+1} - \omega_{N-2}}{h}\right) & \dots & \dots & \dots & \dots & \dots & \dots \\ \left(\frac{1}{h^2} - \frac{\omega_{N+1} - \omega_{N-1}}{h}\right) & \left(-\frac{2}{h^2} + 1\right) & \dots & \dots & \dots & \dots & \dots & \dots & \dots \end{bmatrix}$$

$$F(\vec{\omega}) = \begin{bmatrix} \frac{\omega_2 - 2\omega_1 - \omega_0}{h^2} + \left(\frac{\omega_2 - \omega_0}{2h}\right)^2 + \omega_1 - \ln(x_1) \\ \frac{\omega_3 - 2\omega_2 + \omega_1}{h^2} + \left(\frac{\omega_3 - \omega_1}{2h}\right)^2 + \omega_2 - \ln(x_2) \\ \vdots \\ \frac{\omega_{N+1} - 2\omega_N + \omega_{N-1}}{h^2} + \left(\frac{\omega_{N+1} - \omega_{N-1}}{2h}\right)^2 + \omega_N - \ln(x_N) \end{bmatrix}$$

$$\text{If } h = \frac{1}{2}$$



$x_1 = 1 + \frac{1}{2} = \frac{3}{2} = 1.5$ is the only point where we approximate the soln. $y(x)$ for (1)-(2), $N = 1$

$$f_1(w_0, w_1, w_2) = \frac{w_2 - 2w_1 + w_0}{h^2 = \frac{1}{4}} + \left(\frac{w_2 - w_0}{1}\right)^2 + w_1 - \ln(1.5) = 0.$$

$$\text{Now, } w_0 = 0, \quad w_2 = \ln(2)$$

$$\frac{\ln(2) - 2w_1}{\frac{1}{4}} + \ln^2(2) + w_1 - \ln(1.5) = 0$$

$$\ln(2) - 2w_1 + \frac{1}{4} [\ln^2(2) + w_1 - \ln(1.5)] = 0$$

$$\text{or } \frac{1}{4}w_1 - 2w_1 = -\ln(2) - \frac{1}{4}(\ln^2(2) - \ln(1.5))$$

$$\text{or } w_1 = \frac{-\ln(2) - \frac{1}{4}(\ln^2(2) - \ln(1.5))}{-\frac{7}{4}} \approx 0.407.$$

In general, consider the BVP

$$\begin{cases} y'' = f(x, y, y'), & a < x < b \end{cases} \quad (6)$$

$$\begin{cases} y(a) = \alpha, & y(b) = \beta \end{cases} \quad (7)$$

Theorem 11.1 (Book)

If 1) f is conts on $D = \{(x, y, y') \mid a \leq x \leq b, -\infty < y < \infty, -\infty < y' < \infty\}$

2) f_y and $f_{y'}$ are also conts on D .

3) $f_y(x, y, y') > 0$, for all $(x, y, y') \in D$.

4) There exists such that:

$$|f_{y'}(x, y, y')| \leq M, \text{ for all } (x, y, y') \in D$$

Then, the BVP (6)-(7) has a unique soln.

In our example,

$$f(x, y, y') = -(y')^2 - y + \ln(x)$$

$$f_y(x, y, y') = -1 < 0$$

$$f_{y'}(x, y, y') = -2y'$$

→ There is no assurance of a unique soln.

$$D = \left\{ (x, y, y') \mid \begin{array}{l} 1 < x < 2 \\ -\infty < y < \infty \\ -\infty < y' < \infty \end{array} \right\}$$