

Thm 5.20

Proof:- (the method is stable) (Exercise 1 in book)

Let $\{u_i\}_0^N$ and $\{v_i\}_0^N$ be two discrete solns. of (4)
such that $|u_0 - v_0| < \epsilon$.

Then, for $h > 0$ (fixed)

$$\begin{aligned} |u_i - v_i| &= |u_{i-1} - v_{i-1} + h [\phi(t_{i-1}, u_{i-1}, h) - \phi(t_{i-1}, v_{i-1}, h)]| \\ &\leq |u_{i-1} - v_{i-1}| + hL |u_{i-1} - v_{i-1}| = (1+hL) |u_{i-1} - v_{i-1}| \leq \\ &\leq (1+hL)^2 |u_{i-2} - v_{i-2}| \leq \dots \leq (1+hL)^i |u_0 - v_0| \\ &< (1+hL)^i \epsilon \equiv K \epsilon. \end{aligned}$$

Example 1:- Modified Euler is stable if $f(t, w)$ satisfies a Lip. cond.
and if f is conts on D . $D = \{(t, w) : t \in [a, b], w \in (-\infty, \infty)\}$

$$w_0 = \alpha, \quad w_{i+1} = w_i + \frac{h}{2} [f(t_i, w_i) + f(t_{i+1}, w_i + h f(t_i, w_i))]$$

or

$$w_{i+1} = w_i + h \phi(t_i, w_i, h)$$

Proof:-

(1) We will prove ϕ satisfies a Lipsch. cond.

(2) ϕ is conts.

Then all conclusions of thm 5.20 holds.

① Lip. cond. for Modified-Euler.

$$\begin{aligned}
 & \left| \phi(t, \omega, h) - \phi(t, \bar{\omega}, h) \right| = \frac{1}{2} \left| f(t, \omega) - f(t, \bar{\omega}) + \right. \\
 & \qquad \left. f(t+h, \omega + hf(t, \omega)) - f(t+h, \bar{\omega} + hf(t, \bar{\omega})) \right| \leq \\
 & \leq \frac{1}{2} L |\omega - \bar{\omega}| + \frac{1}{2} L |\omega + hf(t, \omega) - \bar{\omega} - hf(t, \bar{\omega})| \leq \\
 & \leq \frac{1}{2} L |\omega - \bar{\omega}| + \frac{1}{2} L |\omega - \bar{\omega}| + \frac{1}{2} L |f(t, \omega) - f(t, \bar{\omega})| \leq \\
 & L |\omega - \bar{\omega}| + \frac{h}{2} L^2 |\omega - \bar{\omega}| = \left(L + \frac{h}{2} L^2 \right) |\omega - \bar{\omega}|
 \end{aligned}$$

or $\left| \phi(t, \omega, h) - \phi(t, \bar{\omega}, h) \right| \leq \hat{L} |\omega - \bar{\omega}|$
 where $\left(L + \frac{h}{2} L^2 \right) \leq \left(L + \frac{h_0}{2} L^2 \right) \equiv \hat{L}$, for all $h \leq h_0$

② $\phi(t, \omega, h) = \frac{1}{2} [f(t, \omega) + f(t+h, \omega + hf(t, \omega))]$ is clearly
 conts. if f is conts. \Rightarrow Modif. Euler is stable \Rightarrow M.E. is converg.

- Notice that

$$\phi(t, \omega, 0) = \frac{1}{2} f(t, \omega) + \frac{1}{2} f(t, \omega) = f(t, \omega).$$

this implies consistency, since $\lim_{h \rightarrow 0} \frac{y_{i+1} - y_i}{h} = f(t_i, y_i)$

$$\tau_{i+1}(h) = \frac{y_{i+1} - y_i}{h} - \phi(t_i, y_i, h) \xrightarrow{h \rightarrow 0} f(t_i, y_i) - \phi(t_i, y_i, 0) = 0$$

Comment on: i) Convergence, ii) $O(h^2)$ due to (iii)

Multistep Methods. Stability and Convergence.

let's start with a particular case A-B 4th order

$$w_0 = \alpha, w_1 = \alpha_1, \dots, w_3 = \alpha_3. \quad m-1=3$$

$$w_{i+1} = w_i + \frac{h}{24} [55 f(t_i, w_i) - 59 f(t_{i-1}, w_{i-1}) + 37 f(t_{i-2}, w_{i-2}) - 9 f(t_{i-3}, w_{i-3})] \quad (3.1)$$

$i = 3, 4, \dots, N-1$

or

$$w_{i+1} = w_i + h F(t_i, h, w_i, w_{i-1}, w_{i-2}) \quad (3.2)$$

Def. - We say that F satisfies a Lipschitz cond. with respect to the seq. $\{w_j\}_0^N$ if there is $L > 0$ s.t.

for every pair of sequences $\{v_j\}_0^N, \{\tilde{v}_j\}_0^N$ and for $i = m-1, m, \dots, N-1$

$$| F(t_i, h, v_i, \dots, v_{i-3}) - F(t_i, h, \tilde{v}_i, \dots, \tilde{v}_{i-3}) | \leq L \sum_{j=0}^3 | v_{i-j} - \tilde{v}_{i-j} |$$

We show now that F satisfies a Lipschitz cond. w.r. to $\{w_j\}_0^N$ if $f(t, y)$ satisfies a Lipschitz cond. in "y" using that f is Lipsch.

Exercise #2

$$| F(t_i, h, v_i, \dots, v_{i-3}) - F(t_i, h, \tilde{v}_i, \dots, \tilde{v}_{i-3}) | \leq \frac{55L}{24} |v_i - \tilde{v}_i| + \frac{59L}{24} |v_{i-1} - \tilde{v}_{i-1}| + \frac{37L}{24} |v_{i-2} - \tilde{v}_{i-2}| + \frac{9L}{24} |v_{i-3} - \tilde{v}_{i-3}| \leq \frac{59L}{24} \sum_{j=0}^3 |v_{i-j} - \tilde{v}_{i-j}|$$

Exercises:
5.10: 2(a-n), 4-6, 8
5.11: 1, 3, 5(a)(c), 10.

For a more general concept of Lip. cond. for
Multistep methods consider pp. 328.

Def- (L.T.E.)

$$\text{If } w_0 = \alpha, w_1 = \alpha_1, \dots, w_{m-1} = \alpha_{m-1}$$

$$w_{i+1} = a_{m-1} w_i + a_{m-2} w_{i-1} + \dots + a_0 w_{i-(m-1)} + \\ + h F(t_i, h, w_{i+1}, \dots, w_{i-(m-1)}), \quad i = m-1, \dots, N-1.$$

$$\text{Then L.T.E} \equiv \tau_{i+1}(h) = \frac{y_{i+1} - a_{m-1} y_i - \dots - a_0 y_{i-(m-1)}}{h} - \\ - F(t_i, h, y_{i+1}, \dots, y_{i-(m-1)}), \quad i = m-1, \dots, N-1$$

Def.- (Consistency)

Two conditions should be satisfied for consistency

$$i) \lim_{h \rightarrow 0} |\tau_i(h)| = 0, \quad i = m, m+1, \dots, N$$

$$ii) \lim_{h \rightarrow 0} |\alpha_i - y_i| = 0, \quad i = 1, 2, \dots, m-1$$

They say (book) consistency
but I would say convergence
of one-step method.

Consider the IVP

$$y'(t) \equiv 0, \quad y(a) = \alpha, \quad \alpha \neq 0 \quad (5.1)$$

Exact soln: $y(t) \equiv \alpha$

We now apply ^{general} MS method (5) to (5.1)

We will assume that if $f \equiv 0 \Rightarrow F \equiv 0$

Therefore, the MS method reduces to

$$W_{i+1} = a_{m-1} W_i + a_{m-2} W_{i-1} + \dots + a_0 W_{i-(m-1)} \quad (5.2)$$

and any starting method of one-step will be reduced

to $W_{i+1} = W_i, \quad i = 0, \dots, m-2$

then $W_0 = \alpha \Rightarrow W_1 = \alpha = W_2 = \dots = W_{m-2} = W_{m-1}$

and using the MS method

$$\begin{aligned} W_m &= a_{m-1} W_{m-1} + a_{m-2} W_{m-2} + \dots + a_0 W_0 = \\ &= \alpha (a_{m-1} + a_{m-2} + \dots + a_0) \end{aligned}$$

Since, we want the solution of (5.2) to approx. the soln. of (5.1)

then, $W_m = \alpha$ and $\alpha = \alpha (a_{m-1} + a_{m-2} + \dots + a_0)$

$$\Rightarrow \boxed{1 - a_{m-1} - a_{m-2} - \dots - a_0 = 0} \quad (5.3)$$

Eqn. (5.3) is equivalent to say that $\lambda_1 = 1$ is a root of the charact. polyn.

$$P(\lambda) = \lambda^m - a_{m-1} \lambda^{m-1} - \dots - a_0 =$$

let's consider the equation (discrete)

$$W_{i+1} = a_{m-1} W_i + a_{m-2} W_{i-1} + \dots + a_0 W_{i-(m-1)} \quad (6.1)$$

independently of IVP (5.1).

and also consider the corresponding charact. polyn.

$$P(\lambda) = \lambda^m - a_{m-1} \lambda^{m-1} - \dots - a_0.$$

There, $W_n = \lambda^n$, for each 'n' is a soln. if λ is a root of $P(\lambda)$

Since subst. it into (6.1)

$$\begin{aligned} & \lambda^{i+1} - (a_{m-1} \lambda^i + a_{m-2} \lambda^{i-1} + \dots + a_0 \lambda^{i-(m-1)}) = \\ & = \lambda^{i-(m-1)} \left[\lambda^m - a_{m-1} \lambda^{m-1} + \dots + a_0 \right] = 0 \end{aligned}$$

if λ is root of P .

Similar: to what happens in ODE's, if $\lambda_1, \dots, \lambda_m$ are distinct roots of $P(\lambda)$, then every solution of (6.1) can be expressed as

$$W_n = \sum_{i=1}^{m_1} C_i \lambda_i^n \quad \text{and } C_i \text{'s are unique.}$$

In our particular case, $\lambda_1 = 1$ is a root ^{in order} n for $\omega_n \equiv \alpha$, for all n

and

$$\omega_n = \alpha + \sum_{i=2}^{m_1} C_i \lambda_i^n$$

In general, C_i 's are not zero due to roundoff errors

as n grows λ_i^n will grow if $|\lambda_i| > 1$. Therefore, for stable method, we need $|\lambda_i| \leq 1$, $i = 2, \dots, m$.