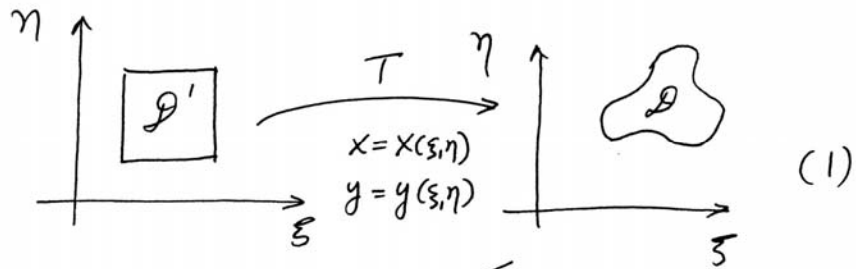


Generalized Curvilinear Coordinates.

Consider the transformation T from the Computational domain \mathcal{D}' into the physical domain \mathcal{D} .



$$\begin{aligned} T^{-1} \\ \xi = \xi(x, y) \\ \eta = \eta(x, y) \end{aligned} \quad (2)$$

Assuming that (Inverse transformation thm.)
 $J(\xi, \eta) = \begin{vmatrix} x_\xi & x_\eta \\ y_\xi & y_\eta \end{vmatrix} \neq 0$, for all $(\xi, \eta) \in \mathcal{D}'$

then, the inverse transformation (2) exists for all $(\xi, \eta) \in \mathcal{D}$

Proof. - If $J(\xi, \eta) \neq 0$, for all $(\xi, \eta) \in \mathcal{D}'$

then, the Jacobian matrix of the inverse transformation

$$\hat{J} = \begin{bmatrix} \xi_x & \xi_y \\ \eta_x & \eta_y \end{bmatrix}$$

Satisfies $\hat{J}^{-1} = J \equiv \begin{bmatrix} x_\xi & x_\eta \\ y_\xi & y_\eta \end{bmatrix}$

Proof. - From equs. (1)-(2) defining the transformation T, T^{-1}
we obtain the equations:

$$\begin{aligned} F(x, y) &= x - X(\xi(x, y), \eta(x, y)) = 0 \quad (2.1) \\ G(x, y) &= y - Y(\xi(x, y), \eta(x, y)) = 0, \text{ for all } (x, y) \in D. \end{aligned}$$

Then,

$$\begin{aligned} F_x(x, y) &= 1 - X_\xi(\xi, \eta)\xi_x - X_\eta(\xi, \eta)\eta_x = 0 \quad (2.2) \\ G_x(x, y) &= 0 - Y_\xi(\xi, \eta)\xi_x - Y_\eta(\xi, \eta)\eta_x = 0, \quad (x, y) \in D \end{aligned}$$

In matrix form:

$$\begin{bmatrix} X_\xi & X_\eta \\ Y_\xi & Y_\eta \end{bmatrix} \begin{bmatrix} \xi_x \\ \eta_x \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad (3)$$

Analogously,

$$\begin{aligned} F_y(x, y) &= 0 - X_\xi \xi_y - X_\eta \eta_y = 0 \\ G_y(x, y) &= 1 - Y_\xi \xi_y - Y_\eta \eta_y = 0 \end{aligned}$$

In matrix form:

$$\begin{bmatrix} X_\xi & X_\eta \\ Y_\xi & Y_\eta \end{bmatrix} \begin{bmatrix} \xi_y \\ \eta_y \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad (4)$$

Combining (3) and (4)

$$\begin{bmatrix} x_{\xi} & x_{\eta} \\ y_{\xi} & y_{\eta} \end{bmatrix} \begin{bmatrix} \xi_x & \xi_y \\ \eta_x & \eta_y \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Therefore,

$$\hat{J} = \begin{bmatrix} \xi_x & \xi_y \\ \eta_x & \eta_y \end{bmatrix} = J^{-1} = \frac{1}{J} \begin{bmatrix} y_{\eta} & -x_{\eta} \\ -y_{\xi} & x_{\xi} \end{bmatrix}$$

Thus,

$$\boxed{\begin{aligned} \xi_x &= \frac{y_{\eta}}{J}, & \xi_y &= \frac{-x_{\eta}}{J} \\ \eta_x &= \frac{-y_{\xi}}{J}, & \eta_y &= \frac{x_{\xi}}{J} \end{aligned}} \quad (5)$$

Second order derivatives: ξ_{xx} , η_{xx} , ξ_{yy} , and η_{yy}
in terms of x_{ξ} , x_{η} , y_{ξ} , y_{η} , $x_{\xi\xi}$, $y_{\xi\xi}$, ..., etc.

Taking another derivative with respect to x from (2.2), we obtain

$$F_{xx} = - \left(x_{\xi\xi} \xi_x^2 + \underbrace{x_{\xi\eta} \xi_x \eta_x}_{=0} + x_{\xi} \xi_{xx} + \underbrace{x_{\eta\xi} \eta_x \xi_x}_{=0} + x_{\eta\eta} \eta_x^2 + x_{\eta} \eta_{xx} \right)$$

$$G_{xx} = - \left(y_{\xi\xi} \xi_x^2 + 2 y_{\xi\eta} \xi_x \eta_x + y_{\xi} \xi_{xx} + y_{\eta\eta} \eta_x^2 + y_{\eta} \eta_{xx} \right) = 0$$

There, the following system of equations⁴ for ξ_{xx} and η_{xx} are obtained

$$\begin{aligned} X_{\xi} \xi_{xx} + X_{\eta} \eta_{xx} &= - (X_{\xi\xi} \xi_x^2 + 2X_{\xi\eta} \xi_x \eta_x + X_{\eta\eta} \eta_x^2) \\ &= -\frac{1}{J^2} (X_{\xi\xi} y_{\eta}^2 - 2X_{\xi\eta} y_{\xi} y_{\eta} + X_{\eta\eta} y_{\xi}^2) \end{aligned}$$

$$y_{\xi} \xi_{xx} + y_{\eta} \eta_{xx} = -\frac{1}{J^2} (y_{\xi\xi} y_{\eta}^2 - 2y_{\xi\eta} y_{\xi} y_{\eta} + y_{\eta\eta} y_{\xi}^2)$$

Solving this nonhomogeneous system of equations, we obtain

$$\xi_{xx} = \frac{1}{J^3} \begin{vmatrix} A & x_{\eta} \\ B & y_{\eta} \end{vmatrix} = \frac{A y_{\eta} - B x_{\eta}}{J^3} \quad (6)$$

where

$$A \equiv X_{\xi\xi} y_{\eta}^2 - 2X_{\xi\eta} y_{\xi} y_{\eta} + X_{\eta\eta} y_{\xi}^2 \quad (6.1)$$

$$B \equiv y_{\xi\xi} \xi_x^2 - 2y_{\xi\eta} y_{\xi} y_{\eta} + y_{\eta\eta} y_{\xi}^2 \quad (6.2)$$

and

$$\eta_{xx} = \frac{1}{J^3} \begin{vmatrix} x_{\xi} & A \\ y_{\xi} & B \end{vmatrix} = \frac{B x_{\xi} - A y_{\xi}}{J^3} \quad (7)$$

Follow a similar procedure and show that

$$\xi_{yy} = \frac{C y_{\eta} - D x_{\eta}}{J^3}, \quad \eta_{yy} = \frac{D x_{\xi} - C y_{\xi}}{J^3} \quad (8)$$

where

$$C \equiv - (X_{\xi\xi} x_{\eta}^2 - 2X_{\xi\eta} x_{\xi} x_{\eta} + X_{\eta\eta} x_{\xi}^2) \quad (9)$$

$$D \equiv - (y_{\xi\xi} x_{\eta}^2 - 2y_{\xi\eta} x_{\xi} x_{\eta} + y_{\eta\eta} x_{\xi}^2)$$

Thm. - If $J(\xi, \eta) \neq 0$, for all $(\xi, \eta) \in \mathcal{D}'$

Show that the inverse of the Laplace system of equations

$$\begin{cases} \xi_{xx} + \xi_{yy} = 0, \\ \eta_{xx} + \eta_{yy} = 0, \end{cases} \quad (x, y) \in \mathcal{D}.$$

can be written as the Winslow's quasilinear elliptic system

$$\begin{cases} \alpha X_{\xi\xi} - 2\beta X_{\xi\eta} + \gamma X_{\eta\eta} = 0, \\ \alpha Y_{\xi\xi} - 2\beta Y_{\xi\eta} + \gamma Y_{\eta\eta} = 0, \end{cases} \quad (\xi, \eta) \in \mathcal{D}'$$

where $\alpha \equiv x_\eta^2 + y_\eta^2$, $\beta \equiv x_\eta x_\xi + y_\xi y_\eta$, $\gamma \equiv x_\xi^2 + y_\xi^2$

Laplace equations in terms of generalized coordinates.

First derivatives: $\hat{f}(\xi, \eta) = f(x(\xi, \eta), y(\xi, \eta))$

$$f(x, y) = \hat{f}(\xi(x, y), \eta(x, y))$$

$$\Rightarrow f_x = \hat{f}_\xi \xi_x + \hat{f}_\eta \eta_x = \frac{1}{J} [\hat{f}_\xi y_\eta - \hat{f}_\eta y_\xi]$$

$$f_y = \hat{f}_\xi \xi_y + \hat{f}_\eta \eta_y = \frac{1}{J} [-\hat{f}_\xi x_\eta + \hat{f}_\eta x_\xi]$$

Thm.- If $T: \mathcal{D}' \rightarrow \mathcal{D}$ is invertible $\left(\begin{array}{l} J(\xi, \eta) \neq 0 \\ (\xi, \eta) \in \mathcal{D}' \end{array} \right)$
 then,

$$f_{xx}(x, y) = \frac{1}{J^2} \left[\hat{f}_{\xi\xi} y_\eta^2 - 2 \hat{f}_{\xi\eta} y_\eta y_\xi + \hat{f}_{\eta\eta} y_\xi^2 \right] \\ + \frac{A}{J^3} (y_\eta \hat{f}_\xi - y_\xi \hat{f}_\eta) + \frac{B}{J^3} (x_\eta \hat{f}_\eta - x_\xi \hat{f}_\xi)$$

$$f_{yy}(x, y) = \frac{1}{J^2} \left[\hat{f}_{\xi\xi} x_\eta^2 - 2 \hat{f}_{\xi\eta} x_\eta x_\xi + \hat{f}_{\eta\eta} x_\xi^2 \right] \\ + \frac{C}{J^3} (y_\eta \hat{f}_\xi - y_\xi \hat{f}_\eta) + \frac{D}{J^3} (x_\xi \hat{f}_\eta - x_\eta \hat{f}_\xi)$$

Corollary.- If $J(\xi, \eta) \neq 0$, $(\xi, \eta) \in \mathcal{D}'$, then

$$\nabla_{x,y}^2 f = f_{xx} + f_{yy} = \\ = \frac{1}{J^2} \left[\alpha \hat{f}_{\xi\xi} - 2\beta \hat{f}_{\xi\eta} + \gamma \hat{f}_{\eta\eta} \right] \\ + \frac{1}{J^3} (\alpha x_{\xi\xi} - 2\beta x_{\xi\eta} + \gamma x_{\eta\eta}) (y_\xi \hat{f}_\eta - y_\eta \hat{f}_\xi) \\ + \frac{1}{J^3} (\alpha y_{\xi\xi} - 2\beta y_{\xi\eta} + \gamma y_{\eta\eta}) (x_\eta \hat{f}_\xi - x_\xi \hat{f}_\eta)$$

Corollary.- If $J(\xi, \eta) \neq 0$, $(\xi, \eta) \in \mathcal{D}'$ and $\begin{cases} \xi_{xx} + \xi_{yy} = 0 \\ \eta_{xx} + \eta_{yy} = 0 \end{cases}$

then,

$$\nabla_{x,y}^2 f = \frac{1}{J^2} (\alpha \hat{f}_{\xi\xi} - 2\beta \hat{f}_{\xi\eta} + \gamma \hat{f}_{\eta\eta}).$$