

in regions where the exact solution is nearly linear and $u'''' \approx 0$.
On finer grids the solution looks better (see Figure 2.6(c) and (d)), and as $h \rightarrow 0$ the method does exhibit second order accurate convergence. But it is necessary to have a sufficiently fine grid before reasonable results are obtained; we need enough grid points to enable the boundary layer to be well resolved.

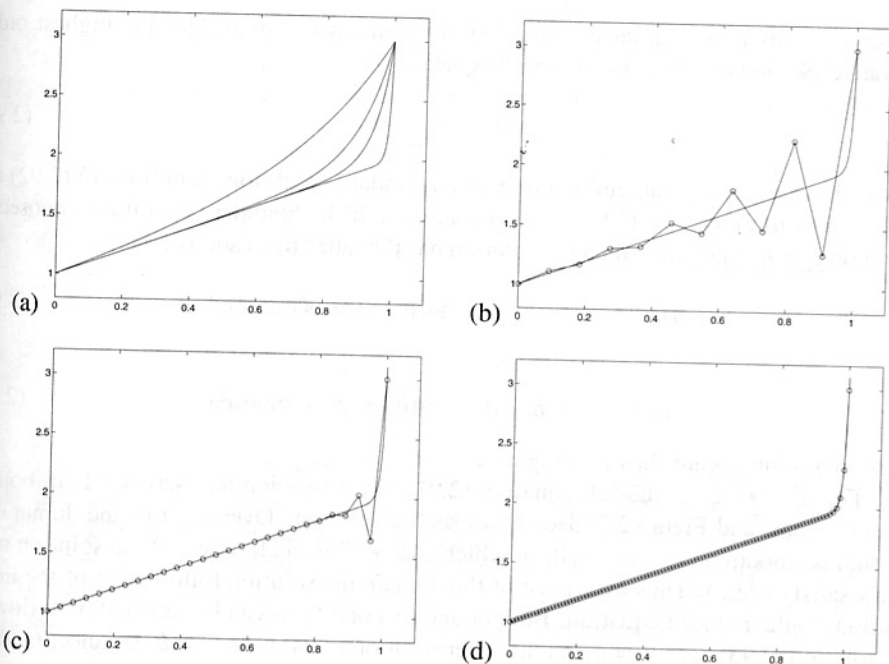


Figure 2.6. (a) Solutions to the steady state advection-diffusion equation (2.88) for different values of ϵ . The four lines correspond to $\epsilon = 0.3, 0.1, 0.05$, and 0.01 from top to bottom. (b) Numerical solution with $\epsilon = 0.01$ and $h = 1/10$. (c) $h = 1/25$. (d) $h = 1/100$.

Compare with Solin for $U''(x) = 0, \quad \alpha \rightarrow \infty$.
 $U(0) = 1, \quad U(1) = 3$

the problem $u''(x) = f(x)$, as the following example illustrates.

Example 2.4. Figure 2.9 shows the error as a function of h for three methods we have discussed on the simplest BVP of the form

$$\begin{aligned}u''(x) &= e^x \quad \text{for } 0 \leq x \leq 3, \\ u(0) &= -5, \quad u(3) = 3.\end{aligned}\tag{2.121}$$

The error behaves in a textbook fashion: the errors for the second order method of Section 2.4 lie on a line with slope 2 (in this log-log plot), and those obtained with the fourth order method of Section 2.20.1 lie on a line with slope 4. The Chebyshev pseudospectral method behaves extremely well for this problem; an error less than 10^{-6} is already

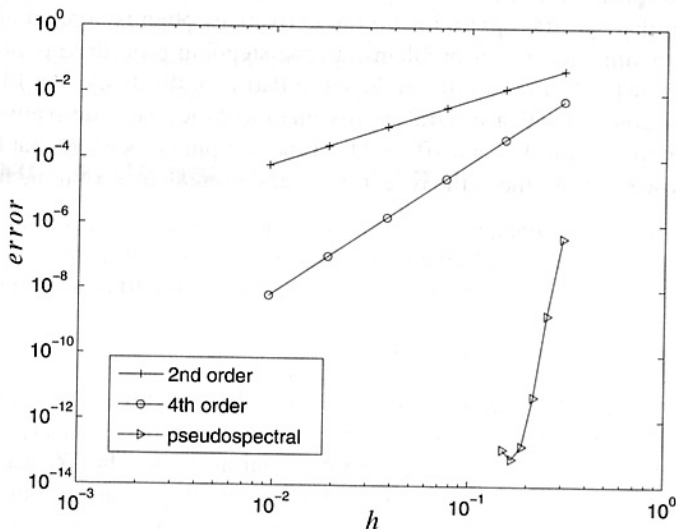


Figure 2.9. Error as a function of h for two finite difference methods and the Chebyshev pseudospectral method on (2.121).